References

Some useful reference books for the issues considered in this course are listed below according to topic. The books indicated by [·], are listed together at the end of the enumerated list.

1. ISOMETRY: [1].

2. EUCLIDEAN AND NON-EUCLIDEAN GEOMETRY: [2, 3, 4, 5, 6, 1, 7, 8, 9, 10].

3. LINE GEOMETRY: [5, 4, 11].

4. KINEMATIC GEOMETRY: [12, 13, 14].

5. COMPUTATIONAL GEOMETRY AND NUMERICAL ANALYSIS: [15, 16, 17].

6. MECHANISMS: [18, 19, 20, 21].

7. KINEMATICS AND DYNAMICS OF ROBOTS: [22, 23].

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