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Bachelor of Engineering, Carleton University, 2016  

DATE: Tuesday April 24, 2018, 13:00 3124 Mackenzie Building  

THESIS TITLE: Optimal Trajectory Planning and Compliant Spacecraft Capture Using a Space Robot  

EXAMINATION BOARD:  
Internal Examiner Hicham Chaoui, Department of Electronics (In Person)  
Member of Department Robert Langlois, Department of Mechanical & Aerospace Engineering (In Person)  
Member of Joint Institute Davide Spinello, University of Ottawa (In Person)  
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Chair/Director of Department or Designate Ronald Miller, Department of Mechanical & Aerospace Engineering (Ex-officio)  
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