CARLETON UNIVERSITY
Department of Mechanical and Aerospace Engineering
MASTER'S THESIS EXAMINATION

CANDIDATE: Justin Kernot
Bachelor of Engineering, Carleton University, 2016

DATE: Wednesday May 01, 2019, 13:00 2014 Minto Case Building

THESIS TITLE: Design and Adaptive Control of a Tendon-Driven Manipulator for the Capture of Non-Cooperative

EXAMINATION BOARD:

Internal Examiner Doron Nussbaum, School of Computer Science (In Person)
Member of Department Rishad Irani, Mechanical & Aerospace Engineering (In Person)
Member of Joint Institute Thomas Uchida, Mechanical Engineering - University of Ottawa (In Person)
Thesis Supervisor Steve Ulrich, Mechanical & Aerospace Engineering (In Person)
Chair/Director of Department or Designate Ronald Miller (Ex-officio)
Dean of Faculty Fred Afagh (Ex-officio)
Dean, Faculty of Graduate and Postdoctoral Affairs Matthias Neufang (Ex-officio)

Ronald Miller, Chair/Director of Department or Designate
Department of Mechanical and Aerospace Engineering

A. Artemer, Assoc. Chair