

CARLETON UNIVERSITY
Department of Mechanical and Aerospace Engineering
MASTER'S THESIS EXAMINATION


CANDIDATE: *Justin Kernot*
Bachelor of Engineering, Carleton University, 2016

DATE: *Wednesday May 01, 2019, 13:00 2014 Minto Case Building*

THESIS TITLE: *Design and Adaptive Control of a Tendon-Driven Manipulator for the Capture of Non-Cooperative*

EXAMINATION BOARD:

Internal Examiner	Doron Nussbaum, School of Computer Science	(In Person)
Member of Department	Rishad Irani, Mechanical & Aerospace Engineering	(In Person)
Member of Joint Institute	Thomas Uchida, Mechanical Engineering - University of Ottawa	(In Person)
Thesis Supervisor	Steve Ulrich, Mechanical & Aerospace Engineering	(In Person)
Chair/Director of Department or Designate	Ronald Miller	(Ex-officio)
Dean of Faculty	Fred Afagh	(Ex-officio)
Dean, Faculty of Graduate and Postdoctoral Affairs	Matthias Neufang	(Ex-officio)

 / *A. Artemer. Assoc. Chair*

Ronald Miller, Chair/Director of Department or Designate
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