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DATE: Friday June 05, 2020, 9:00 VideoConference

THESIS TITLE: Sensor Fusion in Autonomous Navigation using Fast SLAM 3.0 – An improved SLAM Method

EXAMINATION BOARD:

Member of Department  
Steve Ulrich, Mechanical & Aerospace Engineering  
(Video Conference)

Member of Joint Institute  
Dan Neculescu, Mechanical Engineering - University of Ottawa  
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Thesis Supervisor  
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