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| CARLETON UNIVERSITYDepartment of Mechanical and Aerospace EngineeringPhD Comprehensive Exam and Thesis Proposal Defense |
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| ***CANDIDATE:*** | Mahboubeh Zarei |
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| ***DATE:*** | Monday, September 12, 2022, 11:30 p.m. via Video Conference |
| ***THESIS TITLE:*** | **Fault and Anomaly Detection and Isolation in Wheeled Mobile Robots Using Symmetric Track Fusion in a Network of Sensors** |
| **EXAMINATION BOARD:** |
| **Member of Department** | H. Mohamed, Dept. of Mechanical & Aerospace Engineering |
| **Member of Department** | J. Sasiadek, Dept. of Mechanical & Aerospace Engineering |
| **Chair of Defence**  | H. Frei, Dept. of Mechanical & Aerospace Engineering  |
| **Thesis Supervisor** | R. Chhabra, Dept. of Mechanical & Aerospace Engineering |
| **Chair of Department** | R. Miller, Chair, Dept. of Mechanical & Aerospace Engineering (*Ex-officio)* |
| **Dean of Faculty** | L. Kostiuk, Dean, Faculty of Engineering (*Ex-officio*) |
| **Dean, Faculty of Graduate & Postdoctoral Affairs** | P. Smith, Dean, Faculty of Graduate Studies and Research (*Ex-officio*) |
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|  |  |
| Jason Etele, Associate Chair, GraduateDepartment of Mechanical & Aerospace Engineering |  |