Siri Venkata Krishna Sainath Konakalla

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PROFILE

I am a full-time first-year Master of Applied Science student at Carleton University. Experienced in software management as well as hardware systems with a keen interest in the Autonomous systems field and possess strong core concepts in Aerospace & Mechanical engineering.

EDUCATION

Carleton University, ON, Canada

- Master of Applied Science (MASc) in Aerospace Engineering
- GPA 6/6 (Fall term), Coursework Uninhabited Aircraft Systems, Nanomaterials, Introduction to Autonomous Mobile Robots, Smart Materials & Structures.

Jawaharlal Nehru Technological University, Kakinada, India

- **Bachelor of Technology (BTech) in Mechanical Engineering**
- CGPA 9.13/10 equivalent to 3.88/4 (verified by WES) •
- Related courses include Advanced Mechanics of Materials, Design of machine & automobile components, Machine dynamics, Applied Thermodynamics, Heat transfer, Refrigeration & Air conditioning, Fluid mechanics, Hydraulic & Pneumatic systems, Advanced Manufacturing processes, Material science & metallurgy, Finite element method, Computer-aided design & manufacturing, Basic Electronics Engineering, Electrical Technology, and Robotics.

SKILLS & KNOWLEDGE

Technological Skills

- Programming knowledge Python3, C++, Data analysis, Machine learning, MATLAB (basic to intermediate)
- Expert in Industry-standard 3D CAD modeling software Solidworks, CATIA, Siemens NX, AutoCAD 2D
- Engineering Simulations knowledge ANSYS Mechanical, ANSYS Fluent
- Microsoft Office (Word, Excel, PowerPoint), Adobe creative suite (Premiere Pro, Illustrator, Photoshop)

Laboratory Knowledge

- Strength of materials, Fluid mechanics, Modelling & Simulation
- Electrical & Electronics, Heat transfer, Design & metrology
- Fuels & IC engine, Machine tool, Computational methods, Computer-Aided Design & Manufacturing

WORK EXPERIENCE

Linevsha and Thevan Software Technologies Pvt Ltd, India **Robotic Process Automation Engineer - Internship**

Involved in the development of a software management system and process automation of the Route Relay Interlocking (RRI) system for South Central Railways and was responsible for hardware testing.

South Central Railways, Indian Railways, India

Mechanical Engineer - Internship

Supervised regular maintenance of Diesel locomotives, LHB coaches, tested Air-braking systems (advanced pneumatic disc brake system). Coordinated repair & inspection activities (Intermediate overhauling every 9 months). Examined bogie frame, bolster for cracks, damages, and corrosion. Tracked route relay interlocking systems for the safe operation of trains.

CADD Centre Training Services Pvt Ltd. India Diploma in Product design - Full-time student

- Completed training in 3D Cad modeling software such as Solidworks2017, Catia V5 R20, Siemens NX CAD10 and gained hands-on experience with projects.
- Experienced in assembly modeling, drafting, sheet metal design, FEA analysis, and machining simulation.
- Gained basic knowledge on Surface modeling, Bill of materials, Geometric dimensioning & tolerancing.

Graduate Aptitude Test in Engineering (GATE), India Student

Appeared for all India Mechanical engineering examination and ranked among the top 7%.

June 2019 - November 2019

September 2020 - Present

September 2013 – April 2017

May 2018- December 2018

Dec 2019 - March 2020

May 2017 - March 2018

Optimal Path Planning for Autonomous Mobile Robots in Indoor environments

Individual Project (ongoing)

Optimal path length to the destination location with faster convergence while maintaining stable robot posture on uneven surfaces and avoiding obstacles is the primary goal. To achieve higher accuracy in autonomous navigation a combination of a rapidly exploring random tree (RRT) and the Harris hawk's meta-heuristic algorithms would lower computational time, produce paths closer to optimal paths and the robot will start navigating sooner.

Active Polymer-based Flexible Tactile Actuator & their application in Humanoid Robots Jan 2021 - Present Team Project – 4 members (ongoing)

Identified the reality, potential, and challenges with artificial muscle to mimic mammal muscle movements and functions such as self-sensing, self-repair, durability, temperature regulation, and efficiency. Understood the requirements, the current status of research for flexible tactile actuators specifically the Dielectric Elastomer Actuators (DEAs); Twisted & Coiled Polymers (TCPs) for humanoid robot applications are reviewed.

Identifying Forest Canopy Gap Pattern Using Drones to Aid in Harvesting Site Selection Sept 2020 - Dec 2020 Team Project – 3 members

Utilizing UAV technology for data acquisition enhances the operation productivity, lowers equipment costs for harvesting site selection. The project presents a complete UAV design right from the motor, propeller, and battery selection suitable to a particular mission. Orthomosaic maps were analyzed & addressed the practical forestry gap to ensure that forest regrowth is at the forefront of every harvesting operation.

Nanotechnology in Solar Cells – Die-Sensitized Solar Cells (DSSCs)

Team Project – 4 members

The objective was to introduce the Die-Sensitized Solar cells as low-cost alternatives to conventional amorphous silicon solar cells owing to their simplicity in the bulk fabrication process, easy integration with the grid, and smaller overall size with similar solar efficiency. Furthermore, presented the ways of improving DSSCs efficiency.

Structural Analysis of a Bolted Nozzle Flange (Saturn V Rocket Model) Individual Project

The main objective was to assess the margin of safety of the flange bolts. Built a nonlinear finite-element • model to analyze bolted nozzle assembly. Modeled contacts, thermal strains, and gas pressure. Interpreted results for deformation, stress, bolt pre-tension, contact gaps. Studied sensitivity to the key input parameters. Finally verified model with hand calculations

Finite Element Analysis of Bike Crank

Individual Project

The objective was to develop a solution of bike crank to calculate the deformed shape, displacement field, and stress distribution. Developed a static structural model with boundary conditions in Ansys mechanical. Interpreted the results and verified the model by refining mesh. Compared results with the experimental setup and digital image correlation.

Investigation of Material Removal Rate (MRR) on Mild steel – using Taguchi Technique Dec 2016 - March 2017 Team Project – 5 members

Siva Prasad, K., S V K Sainath, K. and Vijay Kumar, B., 2017. Investigation of Material Removal Rate on Mild Steel-using Taguchi Technique. International Journal of Engineering Technology Science and Research, [online] 3(5). Available at: http://www.ijetsr.com/images/short pdf/1495551394 nitttr964 ijetsr.pdf>.

CERTIFICATIONS

- Introduction to Applied Machine Learning
- Machine Learning Algorithms: Supervised Learning Tip to Tail
- Data Analysis with Pandas and Python
- Complete Python3 Bootcamp
- ENGR2000X: A Hands-on Introduction to Engineering Simulations
- Diploma in Product Design

Jan 2021 – Present

Jan 2019 – March 2019

Sept 2020 - Dec 2020

Feb 2019 - March 2019

VOLUNTEER

Velagapudi Ramakrishna Siddhartha Engineering College, India Fundraising and Marketing Volunteer

• Assisted a team of 5 in raising 25% of funds for Annual Cultural & Technical Fest by engaging with individuals, local businesses, and promoting cultural diversity within the community.

National Service Scheme (NSS), India

Event Organizer

• Organized International Yoga day, Blood donation & Medical camps, Swachh Bharat & Tree plantation programs for 864 fellow students to create awareness, and planned events well ahead of time.

MEMBERSHIP_

- American Institute of Aeronautics and Astronautics (AIAA) Student Membership - 1146532
- Royal Aeronautical Society (RAeS) Student Affiliate Membership – 3044583

June 2014 - September 2016

August 2020 - Present

August 2020 - Present

October 2015 - February 2016